## **Refine Search**

## Search Results -

Term	Documents
DRIVE	3153835
DRIVES	875997
FREQUENCY	2298848
FREQUENCIES	546091
FREQUENCYS	76
(22 AND (DRIVE ADJ FREQUENCY)).PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD.	0
(L22 AND DRIVE ADJ FREQUENCY).PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD.	0

US Pre-Grant Publication Full-Text Database

US Patents Full-Text Database

US OCR Full-Text Database

Database:

EPO Abstracts Database JPO Abstracts Database Derwent World Patents Index

IBM Technical Disclosure Bulletins

Search:



Refine Search





Interrupt

## **Search History**

DATE: Monday, December 10, 2007 **Purge Queries** Printable Copy Create Case

Set Nam side by sid		Hit Count S	Set Name result set
DB=P	GPB, USPT, USOC, EPAB, JPAB, DWPI, TDBD; PLUR=YES; OP=ADJ		
<u>L24</u>	L22 and drive adj frequency	0	<u>L24</u>
<u>L23</u>	L22 and residant adj mode	0	<u>L23</u>
<u>L22</u>	(electro-mechanical adj tansducer or transducer)same haptic adj effect	10	<u>L22</u>
<u>L21</u>	haptic adj feedback adj signal\$1 same driv\$6 adj signal\$1	4	<u>L21</u>
<u>L20</u>	haptic adj feedback adj signal\$1	56	<u>L20</u>
L19	haptic adj feedback adj signal\$1	56	L19

<u>L18</u>	L17 and @py<=2002	16	<u>L18</u>
<u>L17</u>	L12 and drive adj frequency	26	<u>L17</u>
<u>L16</u>	L12 and predetermined adj drive adj frequency	0	L16
<u>L15</u>	L14 and predetermined adj drive adj frequency	. 0	<u>L15</u>
<u>L14</u>	L12 adj operational adj mode\$1	0	<u>L14</u>
<u>L13</u>	L12 and resonant adj mode\$1	25	<u>L13</u>
<u>L12</u>	electro-mechanical adj transducer	1979	<u>L12</u>
<u>L11</u>	L10 and drive\$6 frequency	1	<u>L11</u>
<u>L10</u>	L9 and drive adj signal	40	<u>L10</u>
<u>L9</u>	L7 and transducer	57	<u>L9</u>
<u>L8</u>	L7 and electro-mechanical adj transducer	2	<u>L8</u>
<u>L7</u>	L6 and drive\$6 adj signal\$1	105	<u>L7</u>
<u>L6</u>	L5 and drive\$1 signal\$1	105	<u>L6</u>
<u>L5</u>	haptic adj feedback	1209	<u>L5</u>
<u>L4</u>	L2 and operating near2 predetermined adj drive adj frequency	0	<u>L4</u>
<u>L3</u>	L2 and operating near2 predetermined drive adj frequency	0	<u>L3</u>
<u>L2</u>	L1 and drive\$6 signal\$1	18	<u>L2</u>
T 1	hantic adi feedback adi signal\$1	56	T 1

## END OF SEARCH HISTORY